## DIFFEOMORPHISMS WITH MILDLY WILD FRAME OF SEPARATRICES

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**Abstract.** In the paper there is constructed a structural stable diffeomorphism on sphere  $\mathbb{S}^3$  whose nonwandering set consists of n + 1 sinks, n saddles of index 1, one source and the frame of one-dimensional separatrices is mildly wild.

**Introduction.** Let's consider a class  $\Psi_n(\mathbb{S}^3), n \in \mathbb{N}$ , of diffeomorphisms  $f : \mathbb{S}^3 \to \mathbb{S}^3$  with the following properties:

1) the non-wandering set  $\Omega(f)$  consists of 2n + 2 hyperbolic fixed points:  $\omega_1, \ldots, \omega_n, \omega$  are sinks,  $\sigma_1, \ldots, \sigma_n$  are saddles of index 1,  $\alpha$  is a source;

2) one-dimensional unstable separatrices  $\ell_{\sigma_i}$  and  $l_{\sigma_i}$  of saddle point  $\sigma_i, i \in \{1, \ldots, n\}$  satisfy the conditions:  $\bar{\ell}_{\sigma_i} = \{\omega\} \cup \ell_{\sigma_i} \cup \{\sigma_i\}$  and  $\bar{l}_{\sigma_i} = \{\omega_i\} \cup l_{\sigma_i} \cup \{\sigma_i\}$  (here  $\bar{A}$  is closure of the set A).

In Figure 1 the phase portrait of diffeomorphism  $f \in \Psi_n(\mathbb{S}^3)$  is represented. According to [5] (Theorem 2.3) the closure  $\bar{\ell}_{\sigma_i}$  of separatrix  $\ell_{\sigma_i}$  is everywhere smooth except, maybe, at  $\omega$ . So the topological embedding of  $\bar{\ell}_{\sigma_i}$  may be complicated in a neighborhood of the sink. According to [1],  $\ell_{\sigma_i}$  is called *tame* (or *tamely embedded*) if there is a homeomorphism  $\psi : W^s(\omega) \to \mathbb{R}^3$  such that  $\psi(\omega) = O$ , where O is the origin and  $\psi(\bar{\ell}_{\sigma_i} \setminus \sigma_i)$  is a ray starting from O. In the opposite case  $\ell_{\sigma_i}$  is called *wild*. Artin and Fox constructed an example of a wild arc in  $\mathbb{R}^3$  which was not connected with dynamic. Using that example D. Pixton [4] constructed a diffeomorphism from the class  $\Psi_1(\mathbb{S}^3)$  such that arc  $\ell_{\sigma_1}$  is exactly Artin–Fox wild arc. In Figure 2 the phase portrait of this diffeomorphism is represented. Later, in [2] was established that the class  $\Psi_1(\mathbb{S}^3)$  is

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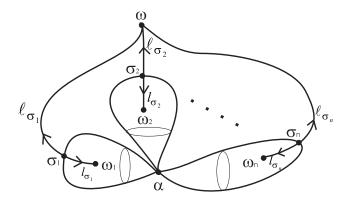


FIGURE 1. The phase portrait of diffeomorphism  $f \in \Psi_n(\mathbb{S}^3)$ 

divided into infinitely many classes of topological conjugacy and the complete topological invariant in each class is the type of embedding of separatrix  $\ell_{\sigma_1}$ . Moreover, in that paper the construction of a model diffeomorphism in each class of topological conjugacy was described.

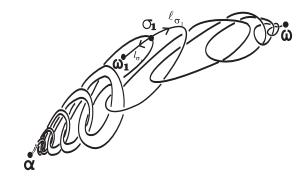


FIGURE 2. Pixton's example

Set  $L_n(\omega) = \bigcup_{i=1}^n \ell_{\sigma_i} \cup \omega$ . For n > 1 the set  $L_n(\omega)$  is a frame of arcs that is a union of arcs with exactly one common point. According to [1] the set  $L_n(\omega)$  is called *tame* if there is a homeomorphism  $\psi : W^s(\omega) \to \mathbb{R}^3$  such that  $\psi(\omega) = O$  and  $\psi(\bar{\ell}_{\sigma_i} \setminus \sigma_i)$  is a ray starting from O for each  $i = 1, \ldots, n$ . In the opposite case  $L_n(\omega)$  is called *wild*. It is clear that a frame is wild if at least one its arc is wild. However, in [3] there is an example of wild frame of arcs in

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 $\mathbb{R}^3$  for which each arc is tame. Moreover, if we delete any arc from such frame then residuary frame is tame. Such a frame is called *mildly wild*. Using this example we construct for  $n \geq 2$  a diffeomorphism  $f \in \Psi_n(\mathbb{S}^3)$  with mildly wild frame of separatrices  $L_n(\omega)$ .

**1. Debruner–Fox example.** Let's consider in  $\mathbb{R}^3$  a three-dimensional ring  $V^0$  given in spherical coordinates as follows:  $\frac{1}{2} \leq \rho \leq 1$  and homothety  $\phi : \mathbb{R}^3 \to \mathbb{R}^3$  given by the formula  $\phi(\rho, \varphi, \theta) = (\frac{1}{2}\rho, \varphi, \theta)$ . Let  $\ell_1^0, \ldots, \ell_n^0$  be simple pairwise disjoint arcs in  $V^0$  satisfying to the following conditions:

- (1)  $\ell_i^0$  has the beginning at the point  $(1, \frac{2\pi i}{n}, 0)$  and end at the point  $(\frac{1}{2}, \frac{2\pi i}{n}, 0)$ ; (2) the rotation by angle  $\frac{2\pi}{n}$  around of the axis OZ translates an arc  $\ell_i^0$  in an arc  $\ell^0_{i+1}$   $(\ell^0_{n+1} = \ell^0_1);$
- (3) the arcs  $\ell_1^0, \ldots, \ell_n^0$  are smooth and have a regular normal projection to the plane XOY (just as is shown in Fig. 3a) for case n = 6).

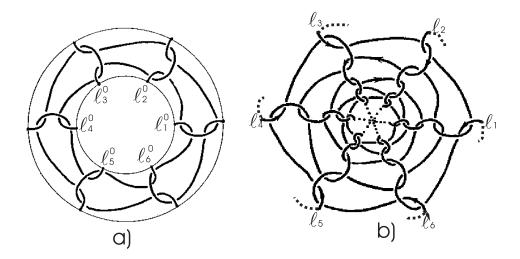


FIGURE 3. Debrunner–Fox example

Set  $\ell_i = \bigcup_{k \in \mathbb{Z}} \phi^k(\ell_i^0)$  and  $L_n = \bigcup_{i=1}^n \ell_i \cup O$ . The projection of the frame  $L_n$  for the case n = 6 on the plane XOY is represented in Fig. 3b. According to [3], the frame  $L_n$  is mildly wild.

**2. Inclusion of mildly wild frame in dynamic.** Set  $\mathbb{D}^2 = \{(y, z) \in \mathbb{R}^2 : y^2 + z^2 \leq 1\}$ . Let's present solid torus  $\mathbb{D}^2 \times \mathbb{S}^1$  as the space of orbits of an action of the group  $G = \{g^n, n \in \mathbb{Z}\}$  on  $\mathbb{D}^2 \times \mathbb{R}^1$  where  $g : \mathbb{D}^2 \times \mathbb{R}^1 \to \mathbb{D}^2 \times \mathbb{R}^1$  is a diffeomorphism given by the formula g(x, y, z) = (x - 1, y, z). For

each arc  $\ell_i \in L_n$  we choose a  $\phi$ -invariant tubular neighborhood  $V(\ell_i)$  and a diffeomorphism  $\zeta_i : V(\ell_i) \to \mathbb{D}^2 \times \mathbb{R}^1$  conjugating the diffeomorphisms  $\phi|_{V(\ell_i)}$ and g.

The required diffeomorphism f we will construct modifying the diffeomorphism  $\phi$  in the style of classical Cherry-flow whose support is contained in a compact 3-ball inside  $V(\ell_i)$ . Let's describe details.

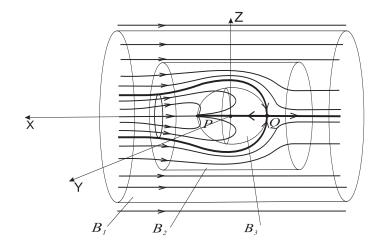


FIGURE 4. Cherry-flow

Let  $\psi_1 \colon \mathbb{R}^3 \to \mathbb{R}$  be a smooth function such that:

- (a)  $\psi_1(x, y, z) = -1$  for any points (x, y, z) outside of the cylinder  $B_1 = \{(x, y, z) \in \mathbb{R}^3 : |x| \le 1, y^2 + z^2 \le \frac{1}{2}\};$ (b)  $\psi_1(x, y, z) < 0$  for any points (x, y, z) outside of a 3-ball  $B_3 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \le 1/16)\};$
- (c)  $\psi_1(x, y, z) > 0$  for any points  $(x, y, z) \in int B_3$ ;
- (d)  $\psi_1(x, y, z)$  is regular at points of 2-sphere  $\partial B_3$ ;
- (e)  $\left|\frac{\partial\psi_1}{\partial x}(\pm\frac{1}{4},0,0)\right| = 1.$

Let  $\psi_2 : \mathbb{R}^3 \to \mathbb{R}$  be a smooth function satisfying to the following conditions:

- (a)  $\psi_2(x, y, z) = 0$  for any points (x, y, z) outside of the cylinder  $B_1$ ;
- (b)  $\psi_2(x, y, z) < 0$  for any points  $(x, y, z) \in int B_1$ ;
- (c)  $\psi_2(x, y, z) = -1$  for any points (x, y, z) belonging to the cylinder  $B_2 = \{(x, y, z) \in \mathbb{R}^3 : |x| \le \frac{1}{2}, y^2 + z^2 \le \frac{1}{4}\}.$

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Flow X we define by the following system of the equations:

$$\begin{cases} \dot{x} = \psi_1(x, y, z) \\ \dot{y} = y \cdot \psi_2(x, y, z) \\ \dot{z} = z \cdot \psi_2(x, y, z) \end{cases}$$

The flow X has exactly two fixed points: a saddle at the point Q =(-1/4, 0, 0) and a sink at the point P = (1/4, 0, 0), both points are hyperbolic (see Fig. 4). Unstable separatrices of the point Q are the interval

solution (see Fig. 1). Constant separatives of the point q are the interval  $\{|x| < \frac{1}{4}, y = 0, z = 0\}$ , (laying in the basin of the attracting point P) and the set  $\{x < -\frac{1}{4}, y = 0, z = 0\}$ . Let  $g_X$  be a shift of unit time of the flow X. By the construction  $g_X$  coincides with shift onf time unit of a flow  $\frac{\partial}{\partial t}$  outside of the cylinder  $B_1$ , belonging to the interior  $\mathbb{D}^2 \times \mathbb{R}$ . Let's define the diffeomorphism  $\overline{f} : \mathbb{R}^3 \to \mathbb{R}^3$ as follows:

(a) *f̄* coincides with φ outside V(ℓ<sub>i</sub>).
(b) *f̄* coincides with ζ<sub>i</sub><sup>-1</sup> ∘ g<sub>X</sub> ∘ ζ<sub>i</sub> inside V(ℓ<sub>i</sub>).

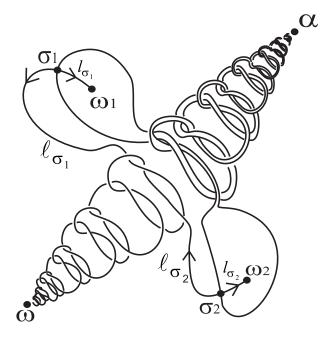


FIGURE 5. Phase portrait of the diffeomorphism  $\Psi_2(\mathbb{S}^3)$  with mildly wild frame of separatrices

**3. Projection on**  $\mathbb{S}^3$ . Let's define the stereographic projection  $\vartheta : \mathbb{S}^3 \setminus (0,0,0,1) \to \mathbb{R}^3$  by the formula  $\vartheta(x_1,x_2,x_3,x_4) = (\frac{x_1}{1-x_4},\frac{x_2}{1-x_4},\frac{x_3}{1-x_4}).$ 

Set 
$$f(x) = \begin{cases} \vartheta^{-1}(f(\vartheta(x))), & x \in \mathbb{S}^3 \setminus \{0, 0, 0, 1\} \\ x, & x = (0, 0, 0, 1). \end{cases}$$

By construction the non-wandering set of the constructed diffeomorphism f is fixed, hyperbolic and consists of (n+1) sinks  $\omega_1 = \vartheta^{-1}(\zeta_1^{-1}(P)), \ldots, \omega_n = \vartheta^{-1}(\zeta_n^{-1}(P)), \omega = \vartheta^{-1}(O), n$  saddles  $\sigma_1 = \vartheta^{-1}(\zeta_1^{-1}(Q)), \ldots, \sigma_n = \vartheta^{-1}(\zeta_n^{-1}(Q))$  of index 1 and one source (0, 0, 0, 1). Thus, the diffeomorphism f belongs to the class  $\Psi_n(\mathbb{S}^3)$  and has Debruner–Fox frame of separatrices. The phase portrait of the diffeomorphism for the case n = 2 is represented in Figure 5.

REMARK 1. Notice that the construction above can be used for any frame  $L_n(\omega)$ , not only Debruner-Fox. For instance, by this construction we can realize Pixton's example (see Fig. 2).

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